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Darryl Mexic (202) 293-7060
Soichiro KATO, et al.
SEPARATOR, LINEAR GUIDE USING THE
SEPARATION AND LINEAR MOTION
APPARATUS

FIG. 1

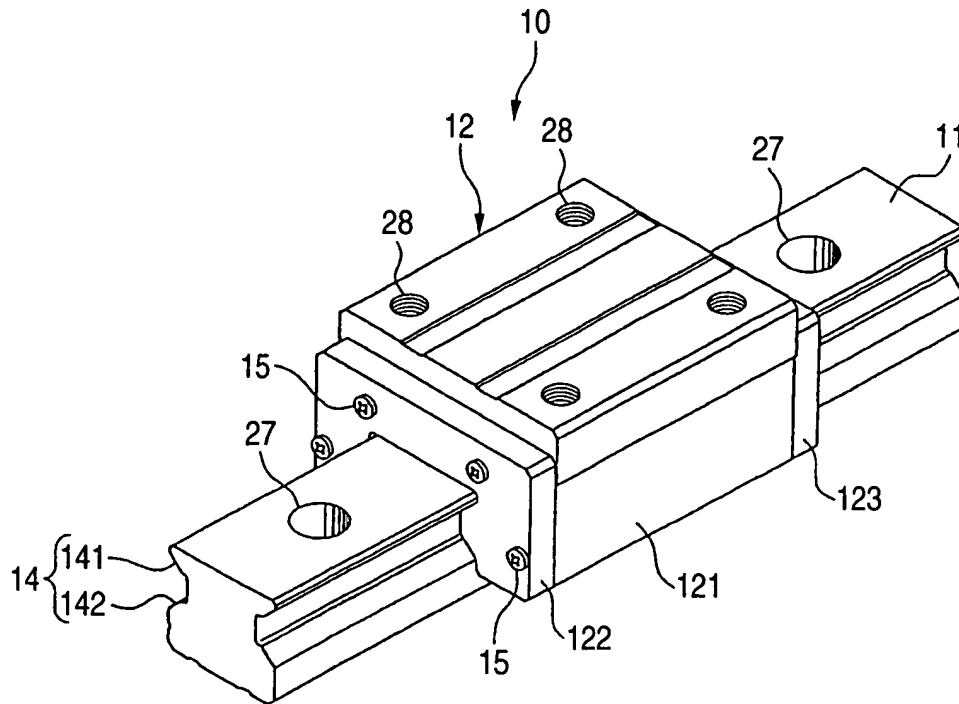


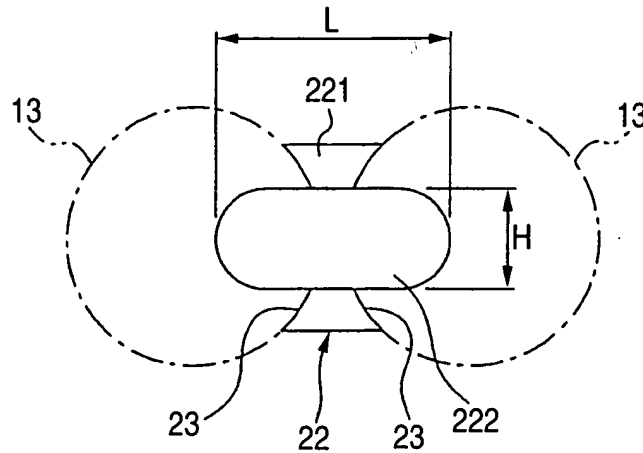
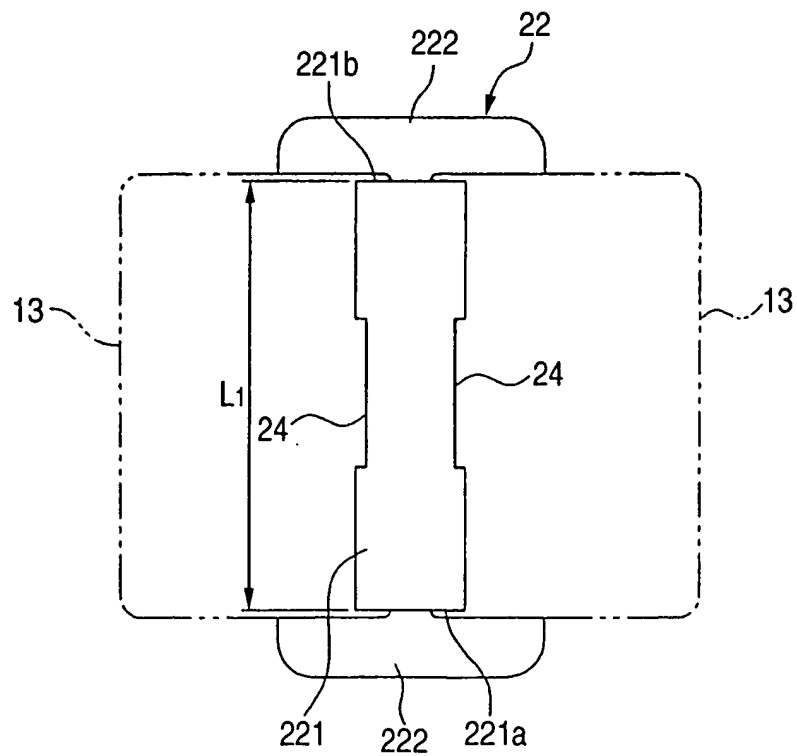
FIG. 4*FIG. 5*

FIG. 6

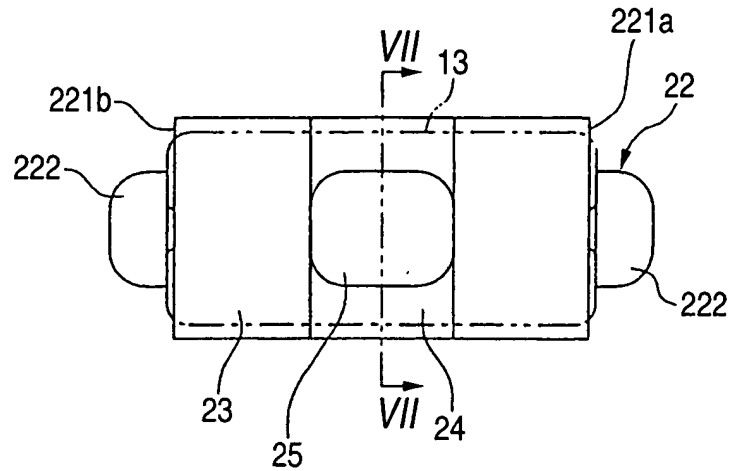


FIG. 7

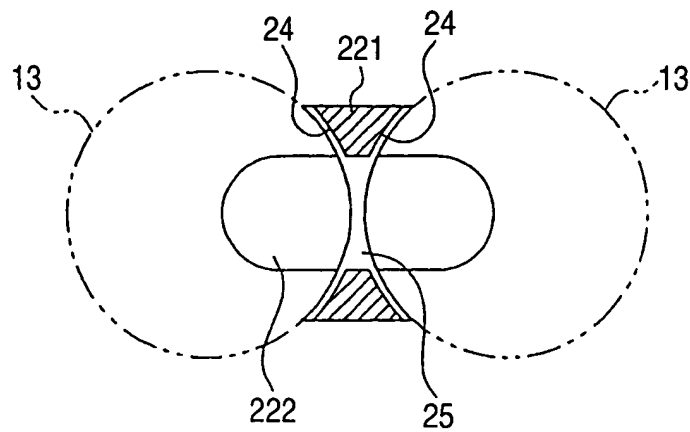
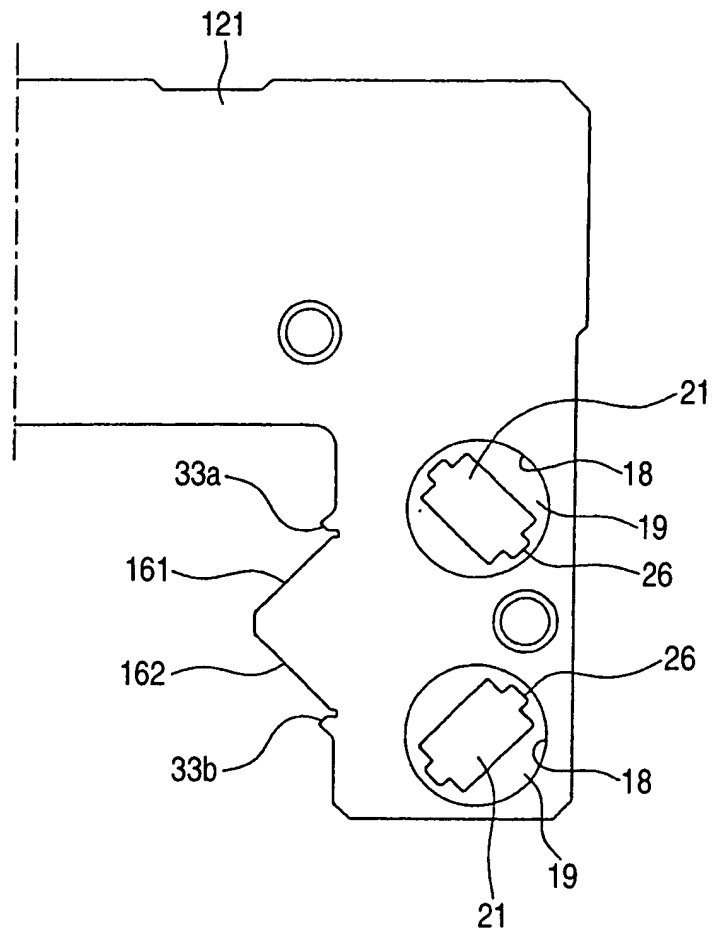


FIG. 8



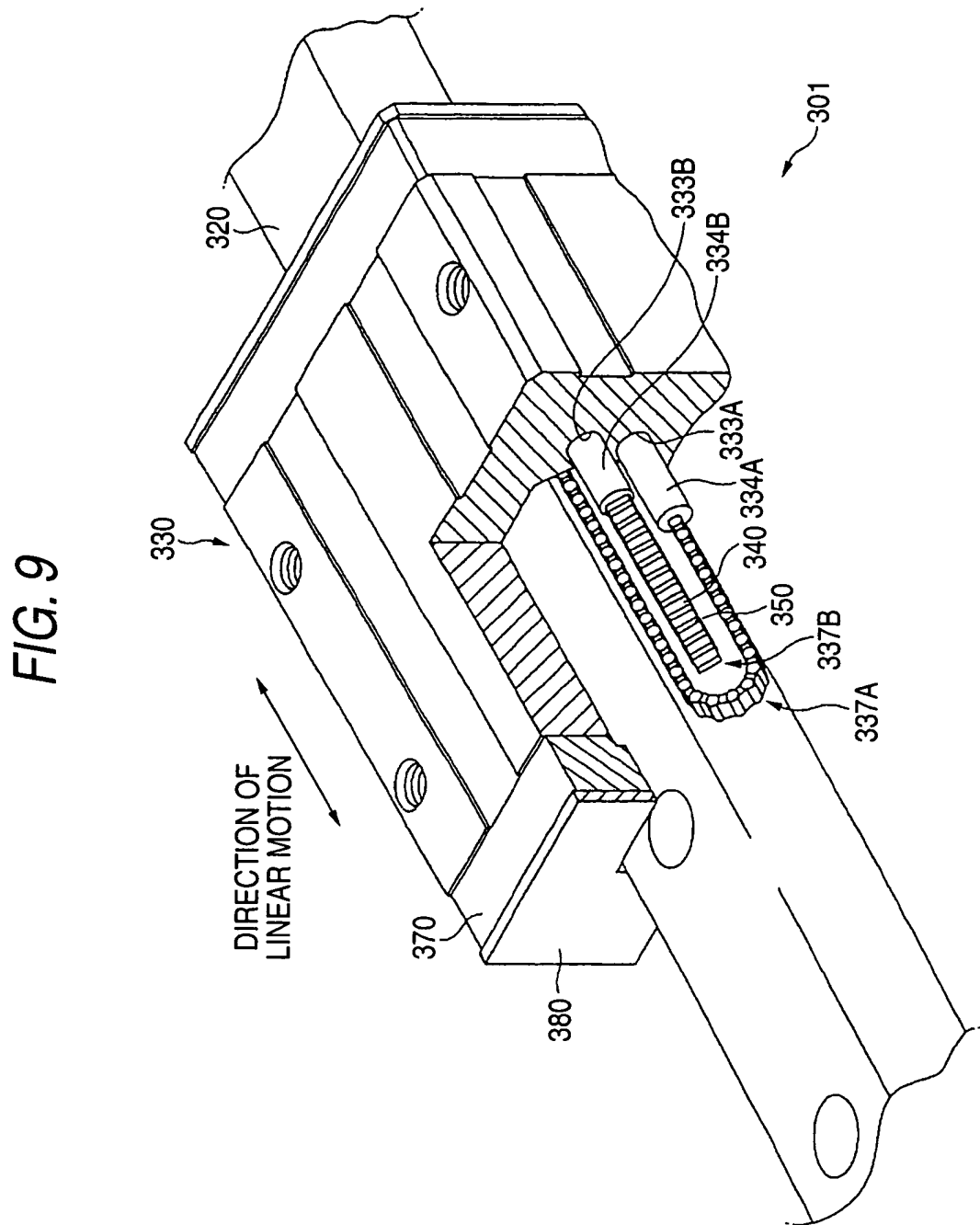
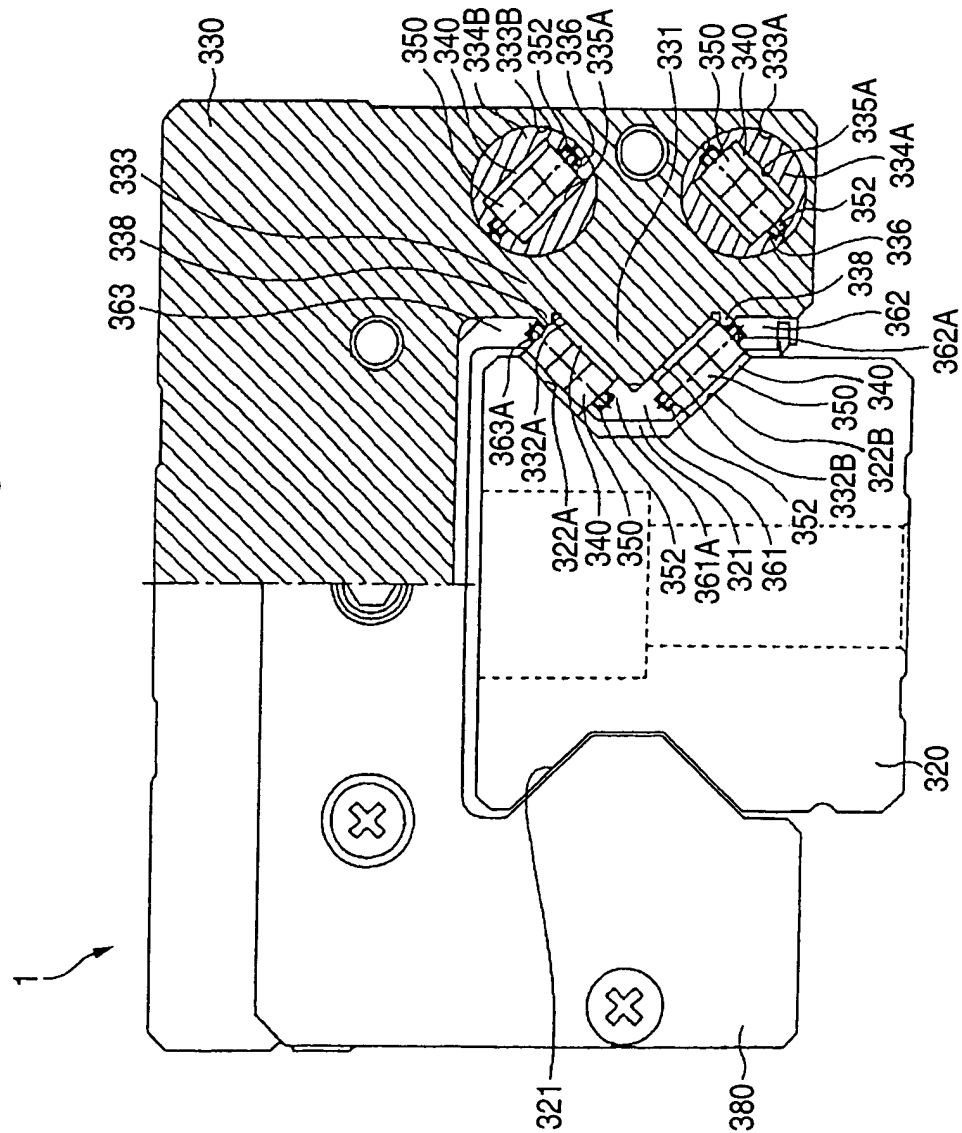


FIG. 10



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FIG. 11

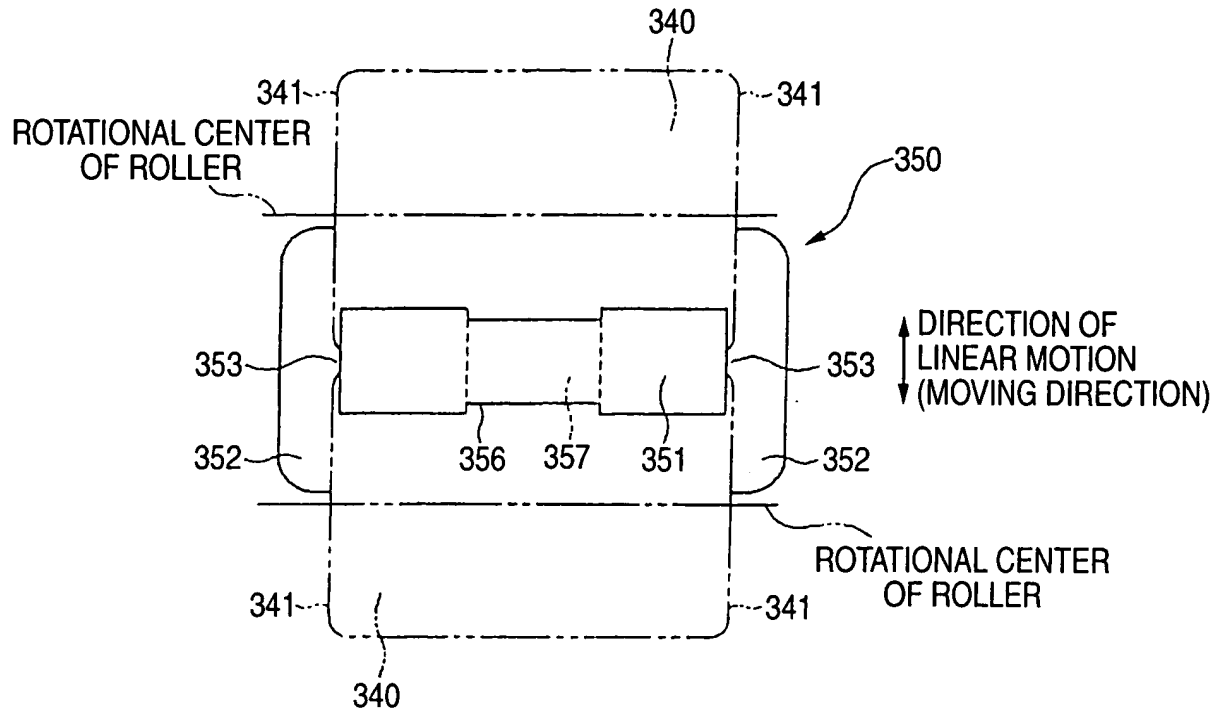
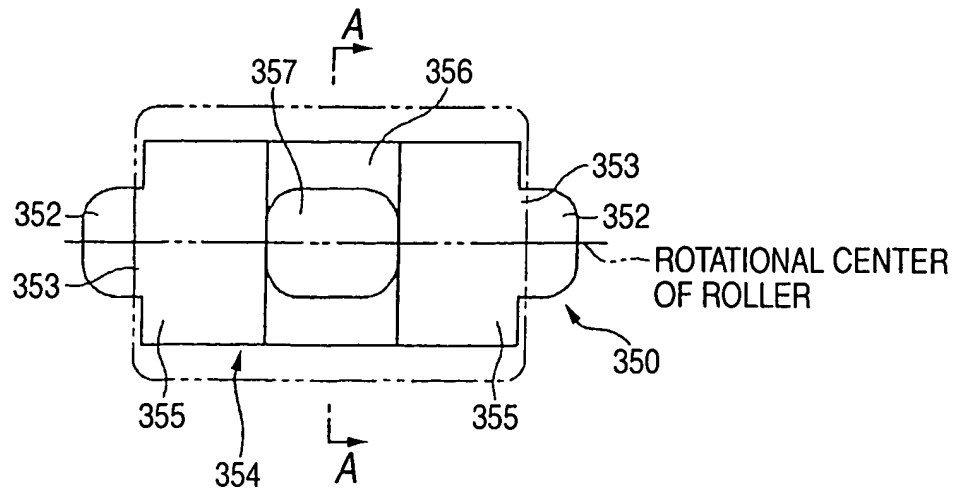


FIG. 12



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FIG. 13

A-A

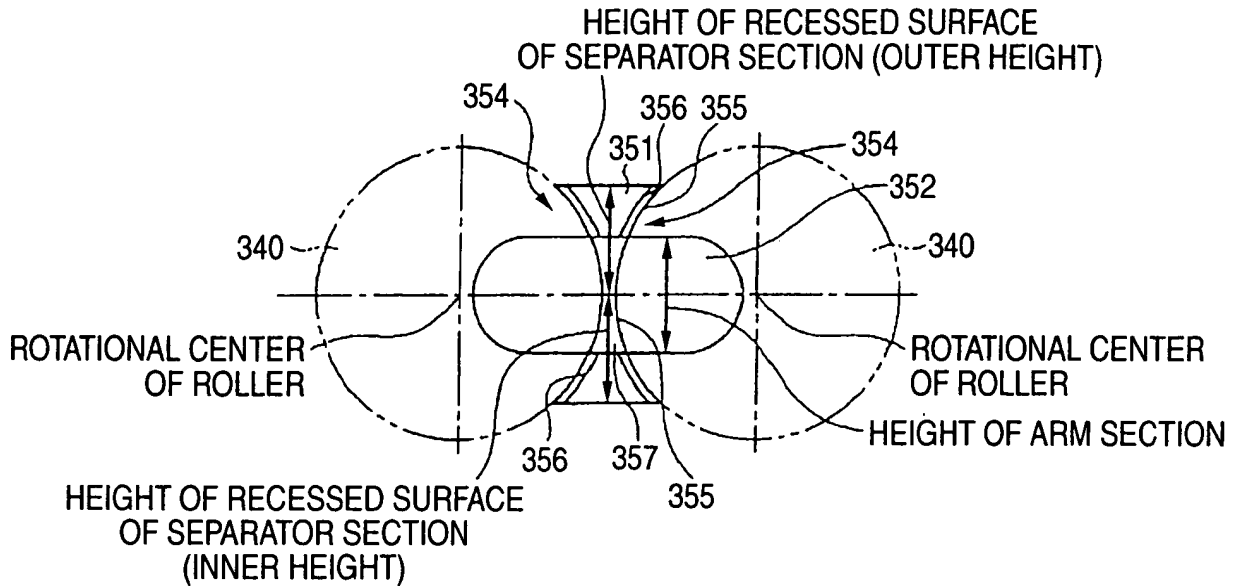


FIG. 14

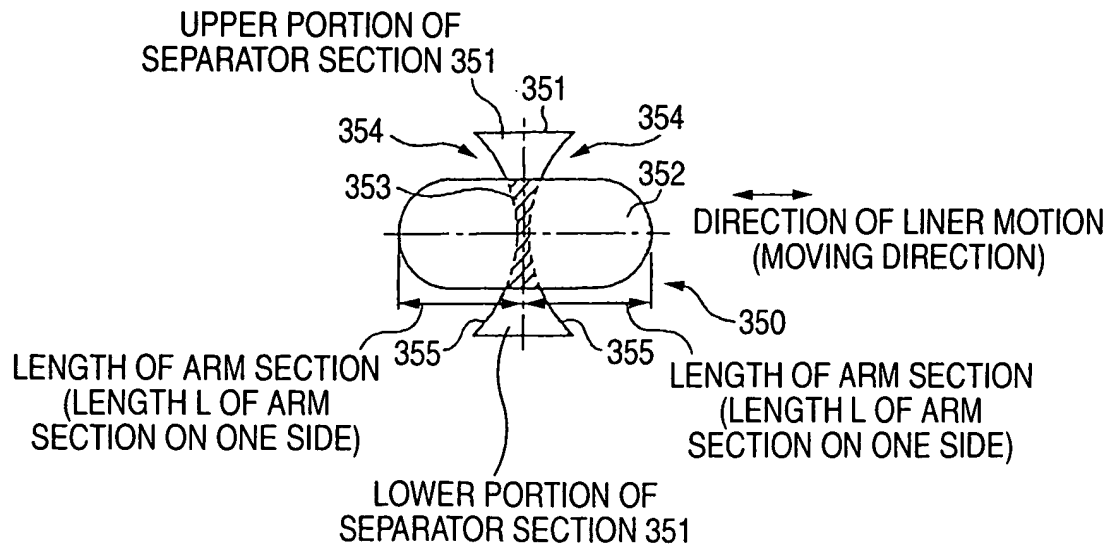
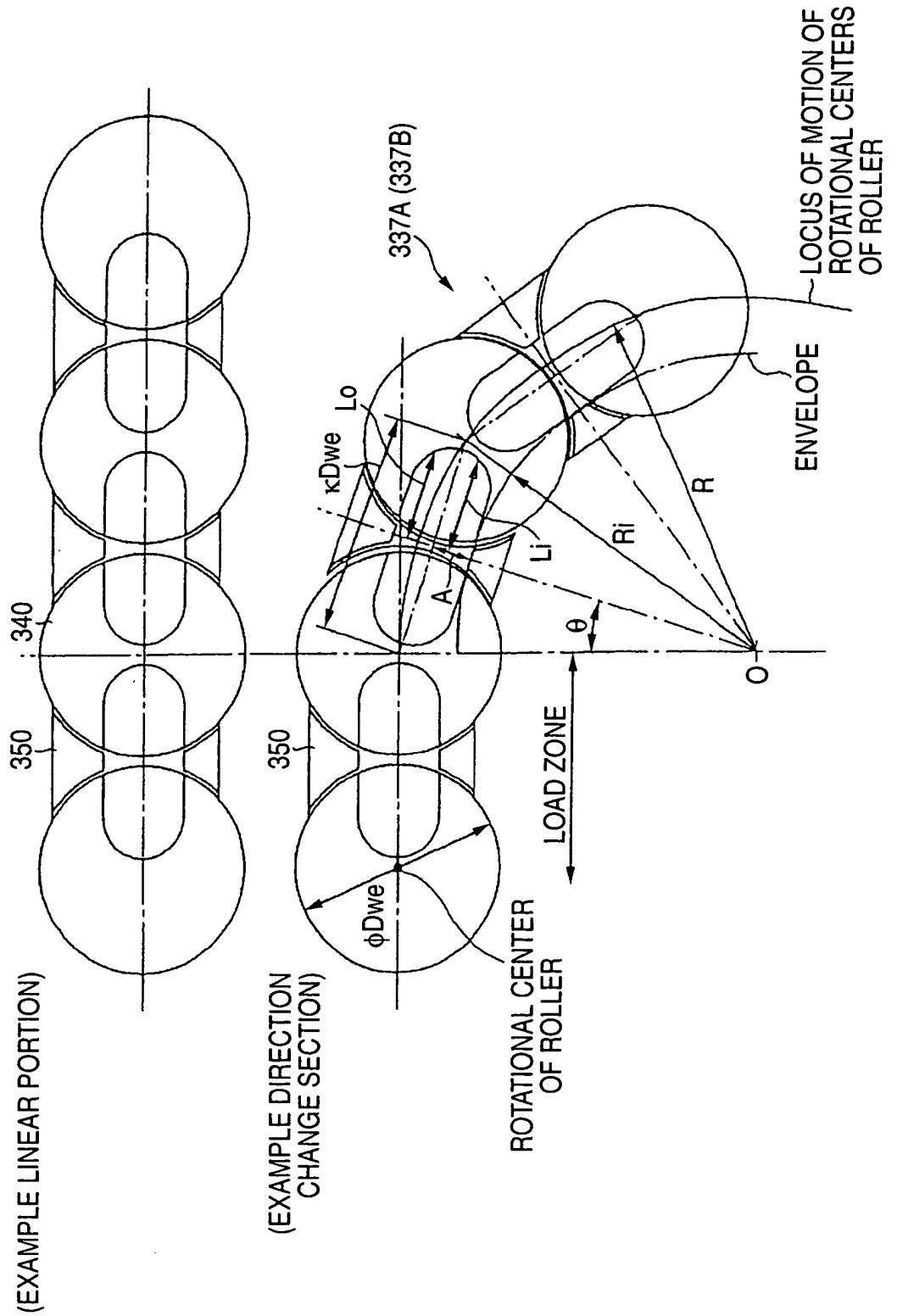


FIG. 15



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FIG. 16

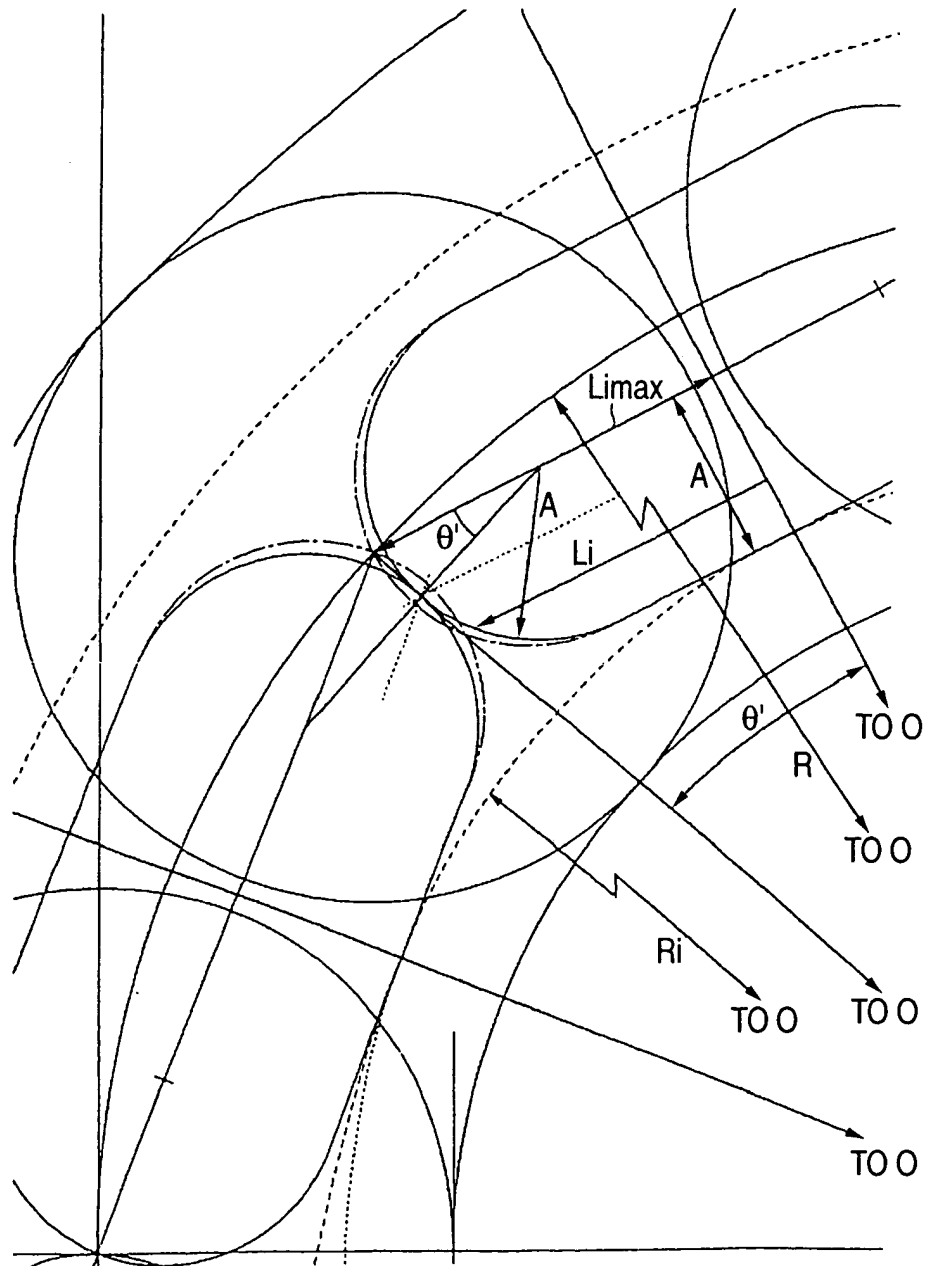


FIG. 17

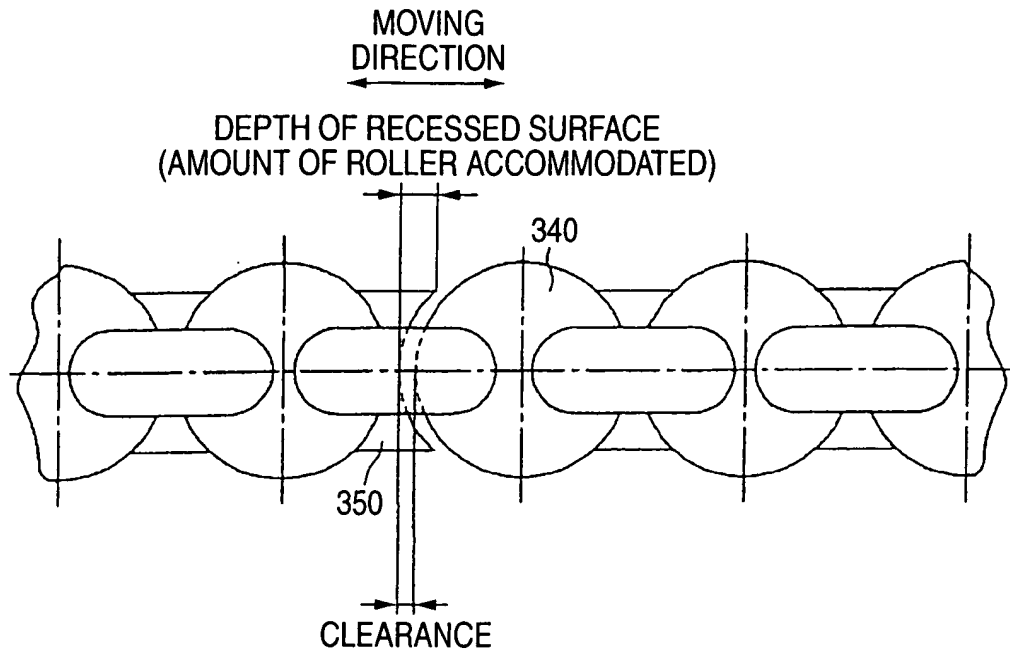


FIG. 18

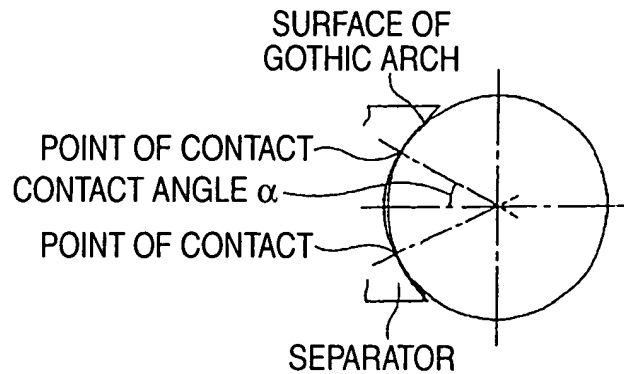


FIG. 19

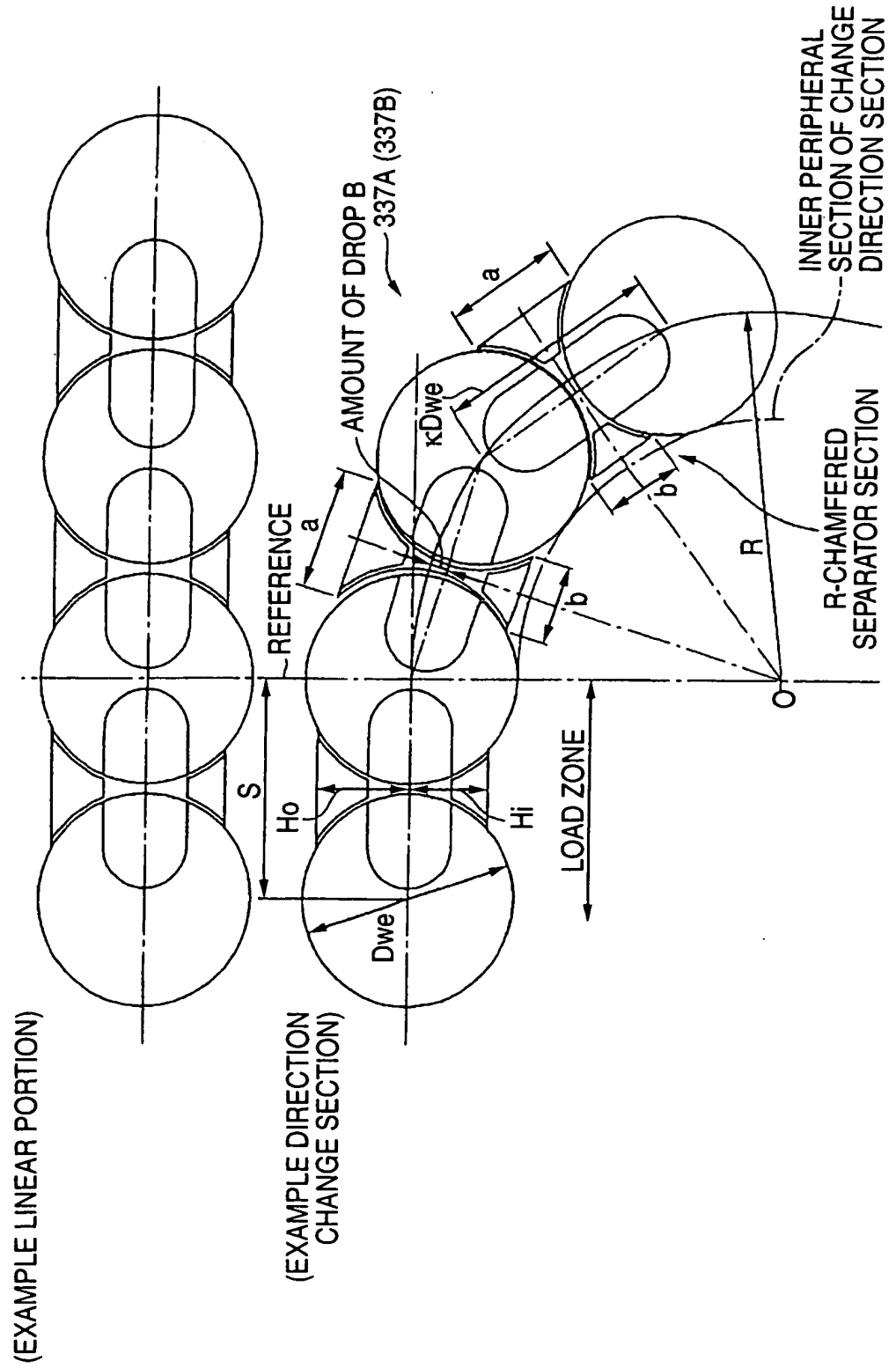


FIG. 20

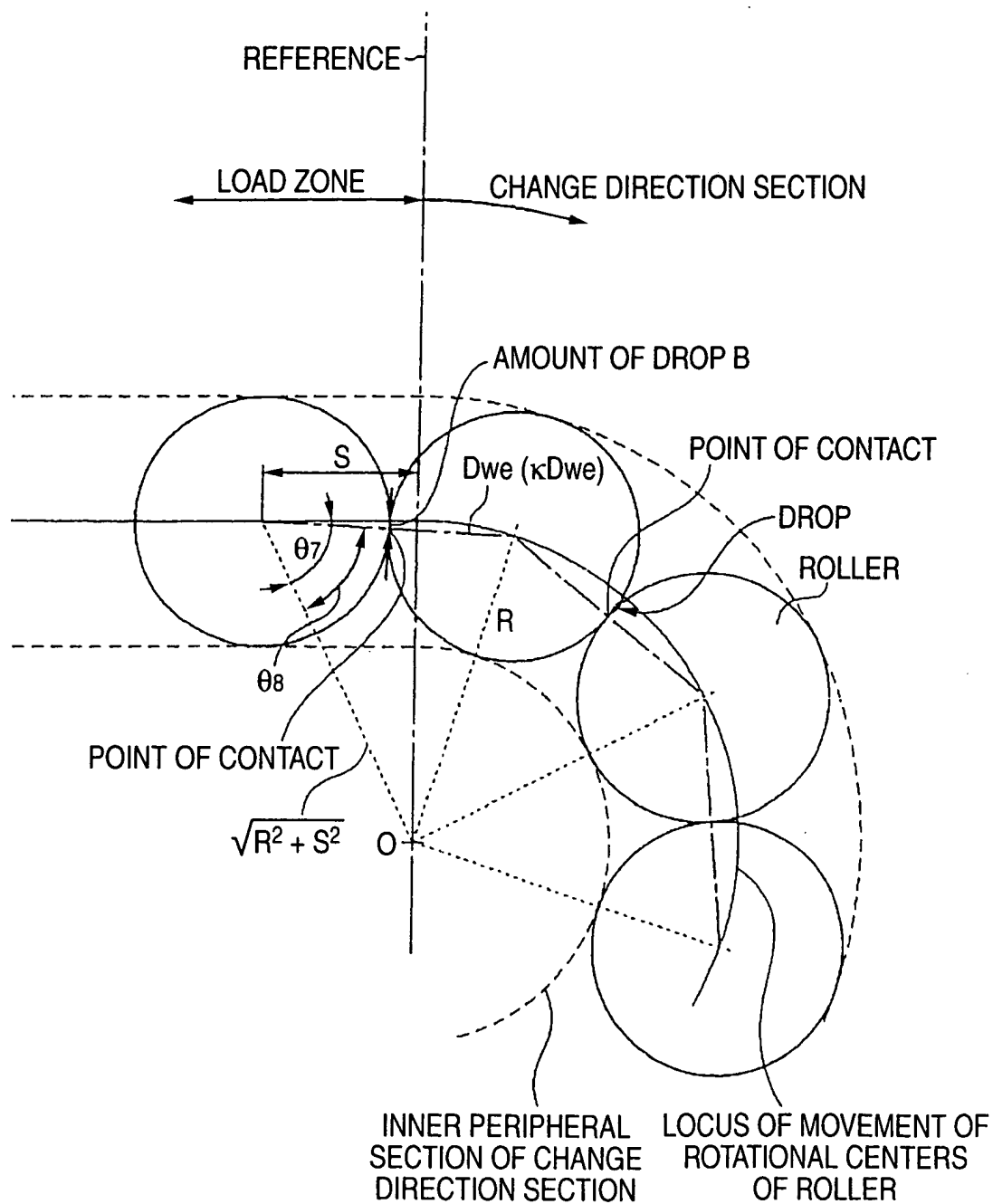


FIG. 21

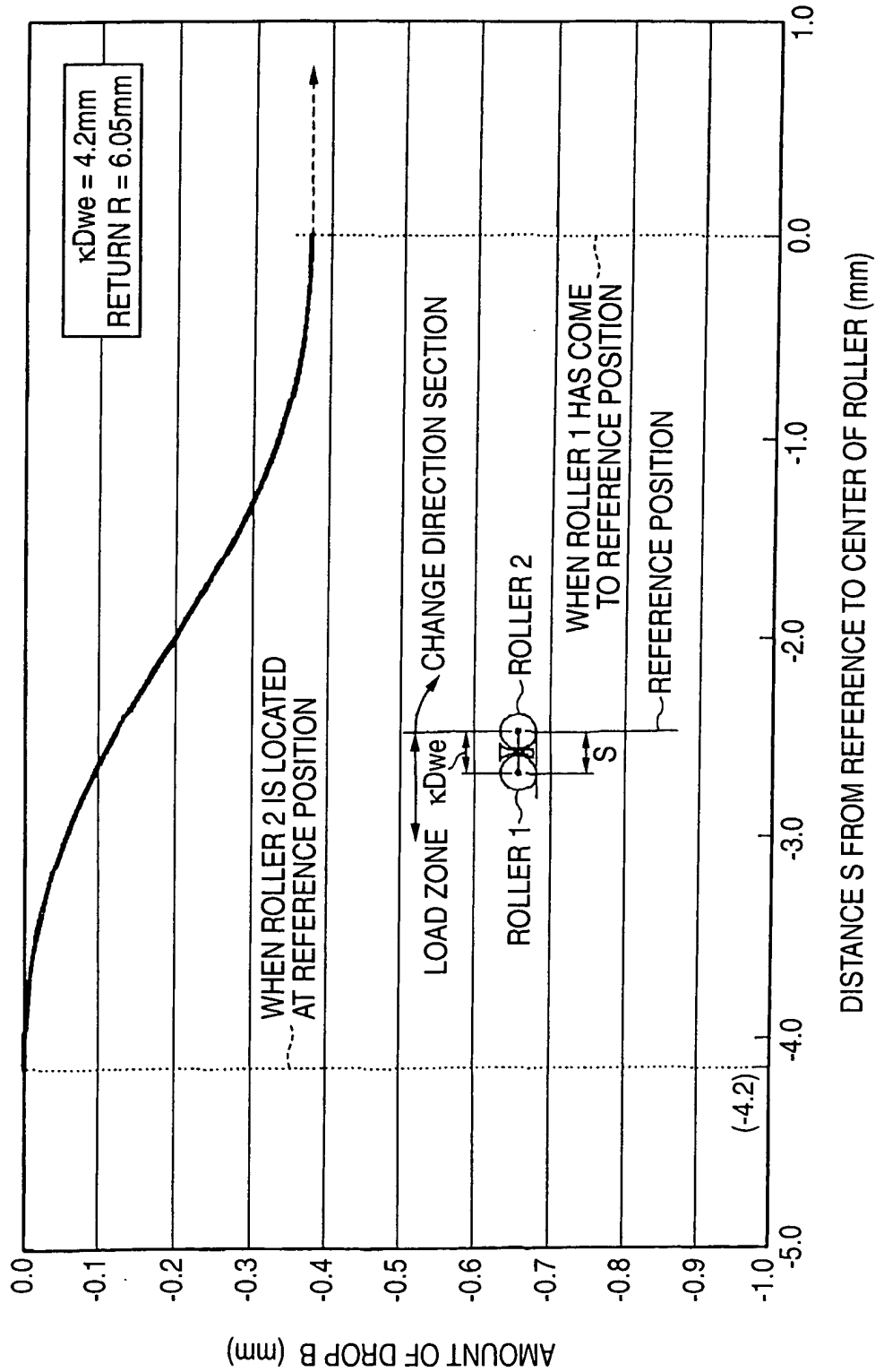


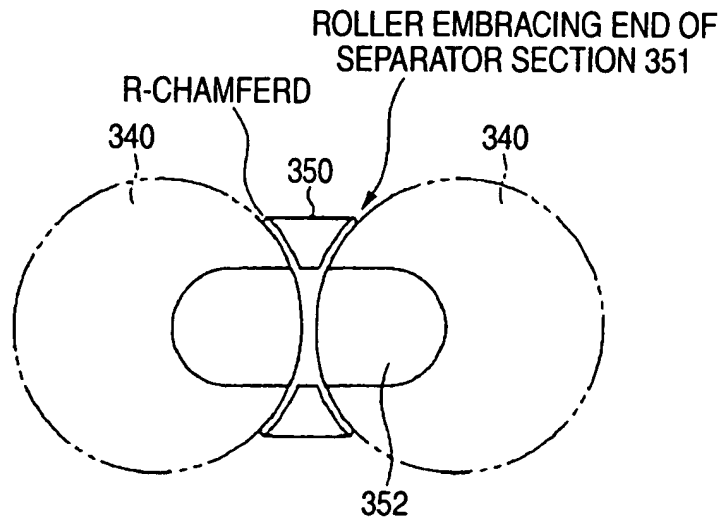
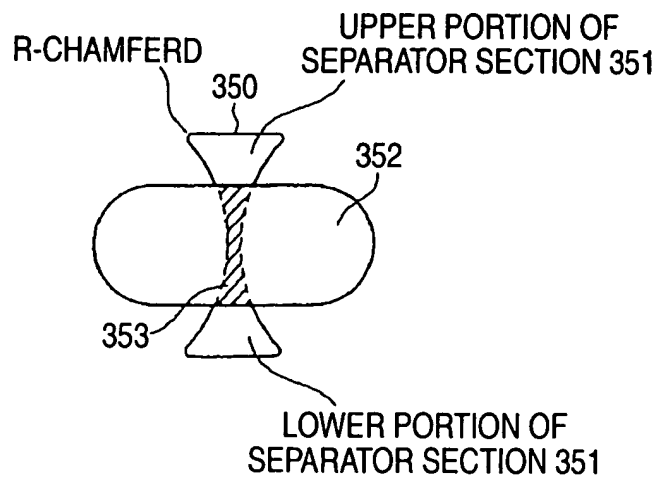
FIG. 22**FIG. 23**

FIG. 24A

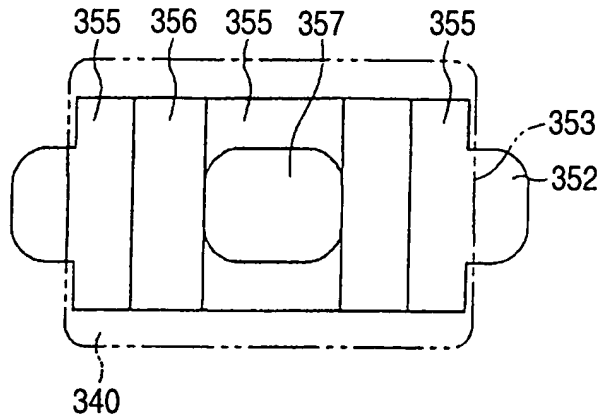


FIG. 24B

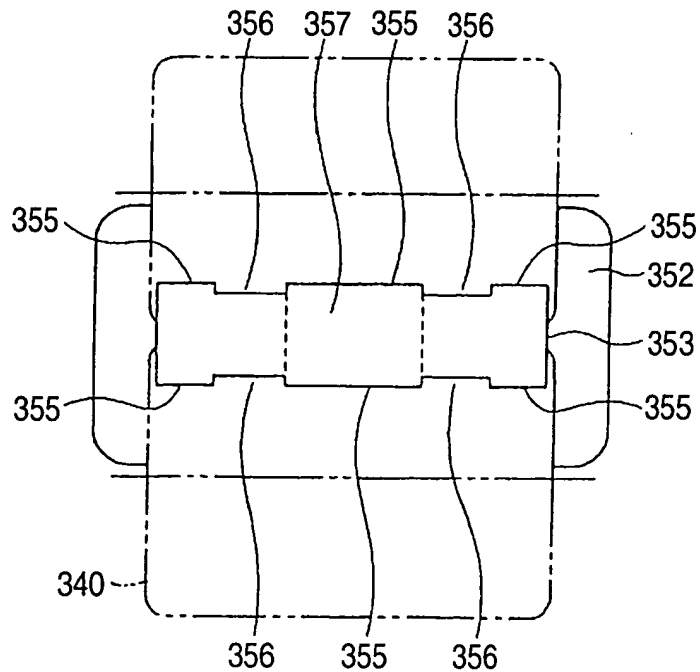


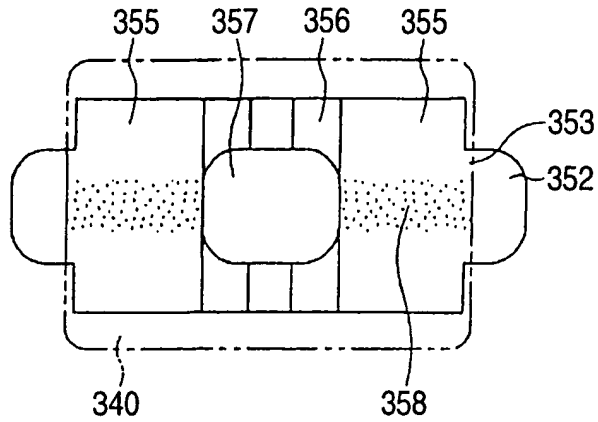
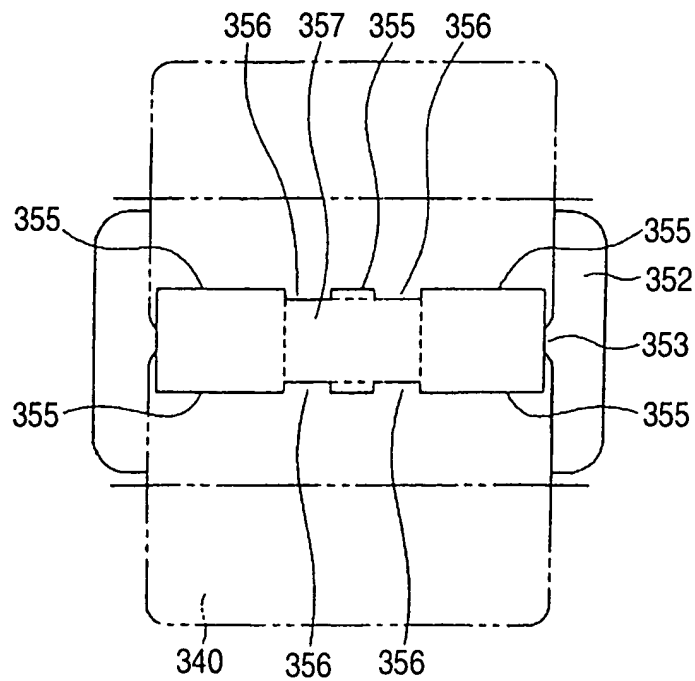
FIG. 25A*FIG. 25B*

FIG. 26

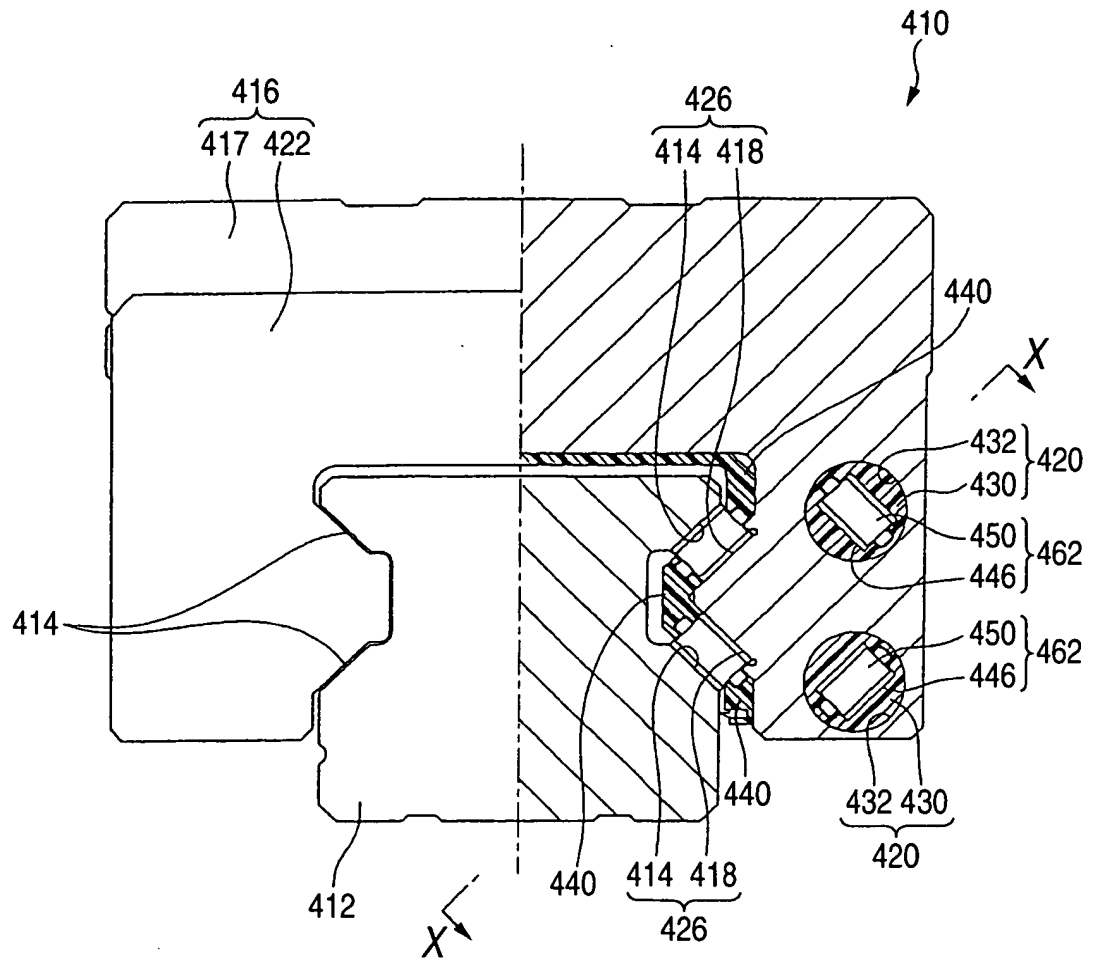


FIG. 27

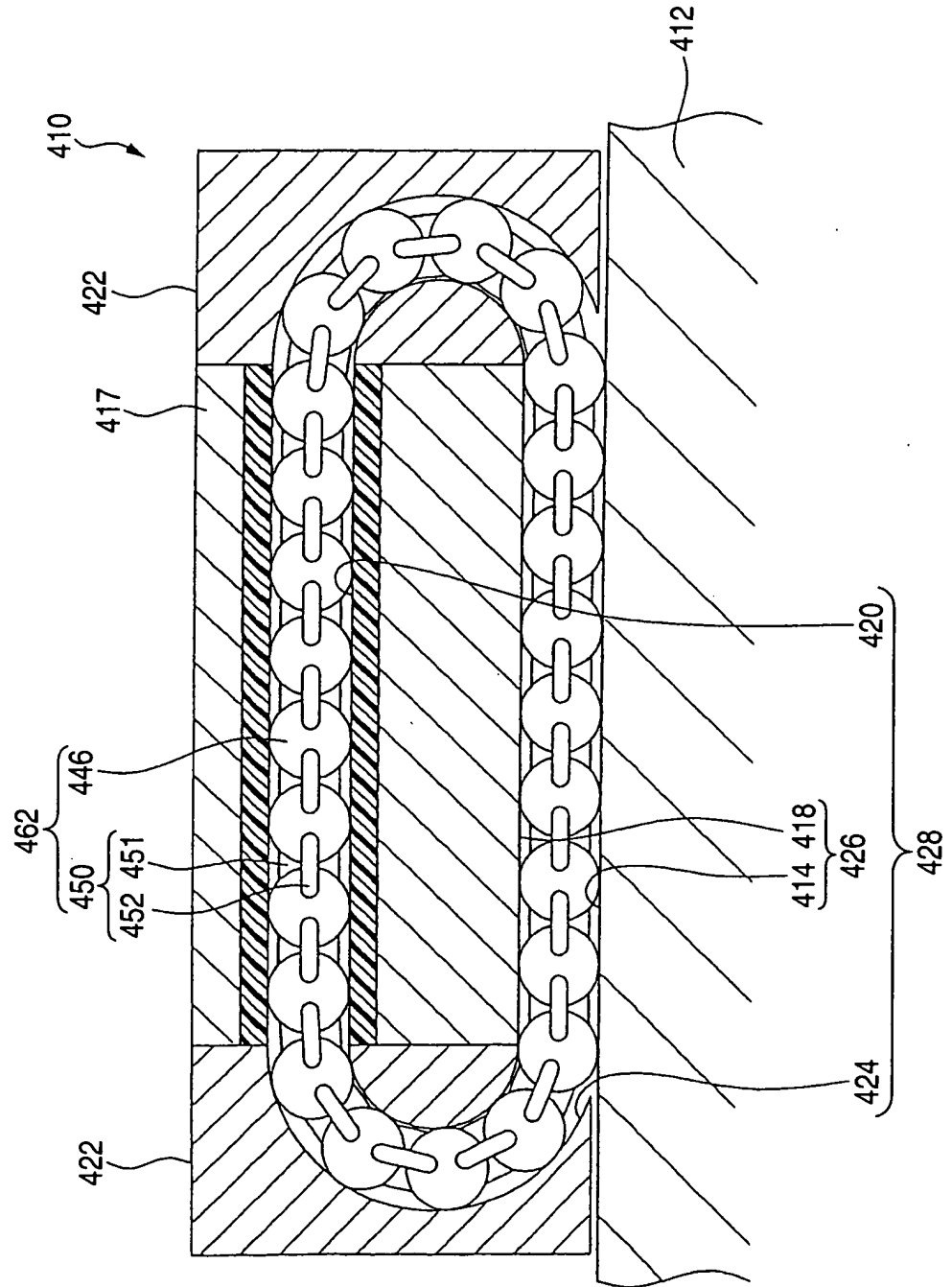


FIG. 28

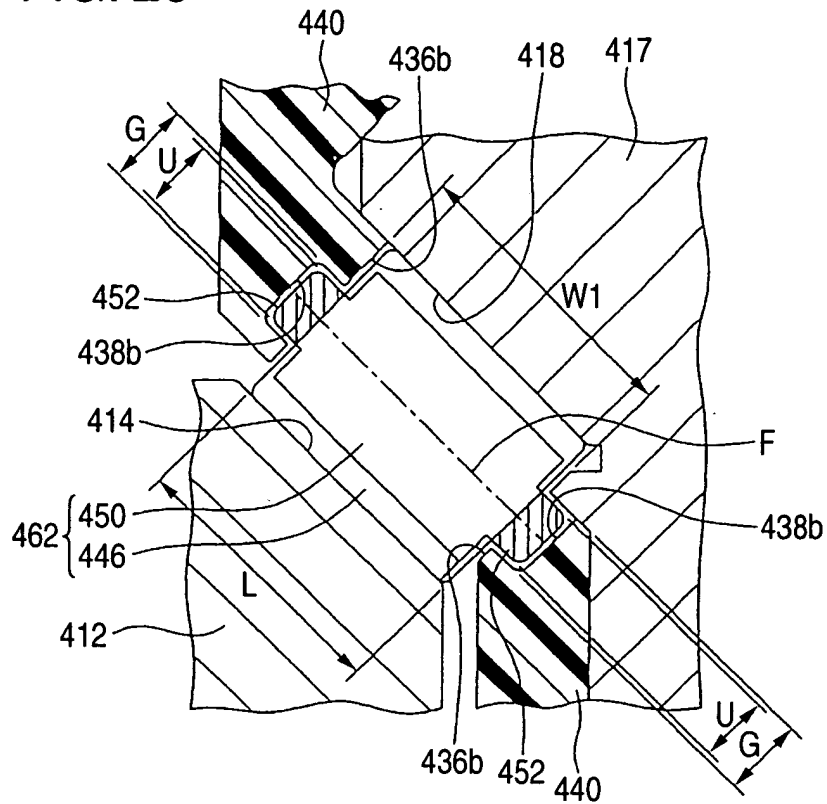


FIG. 29

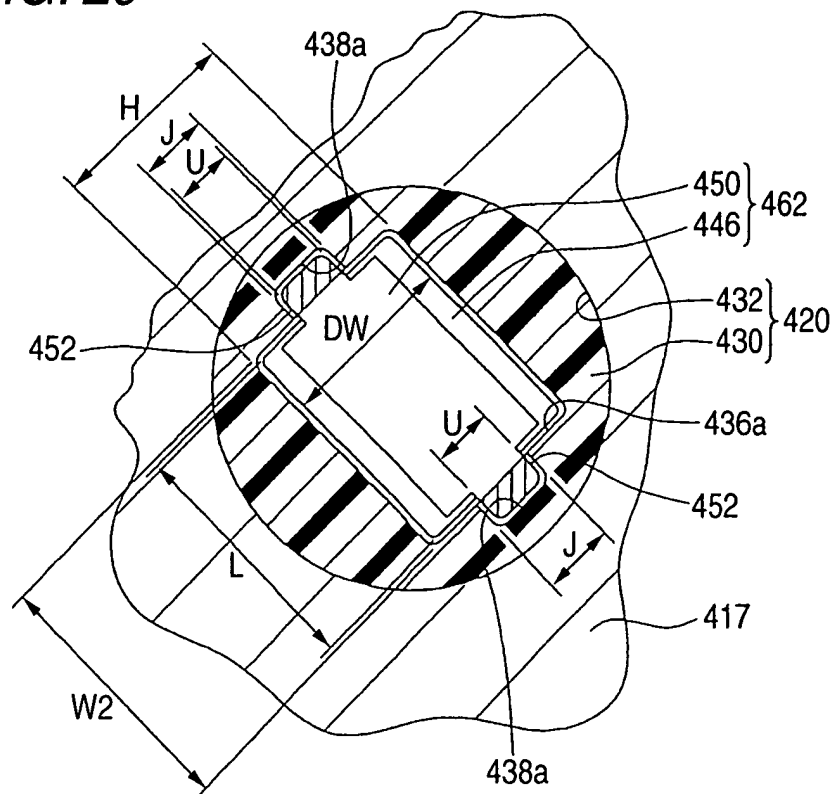


FIG. 30A

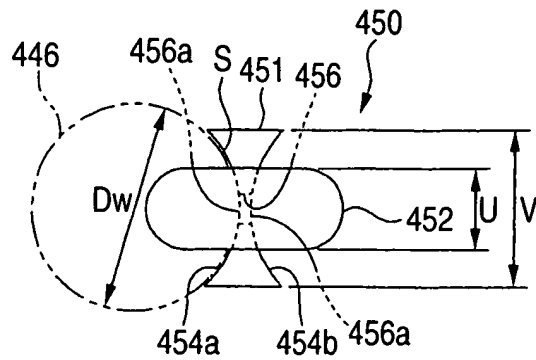


FIG. 30B

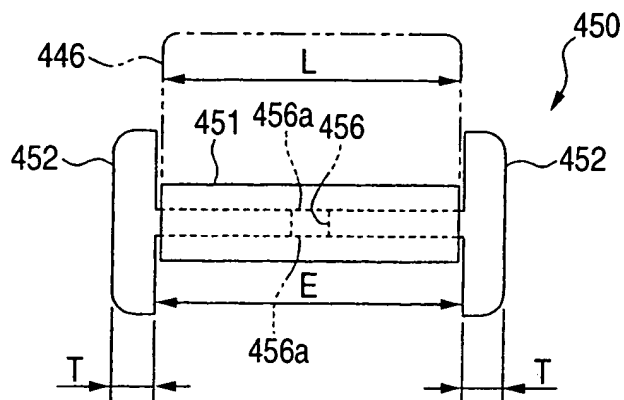


FIG. 30C

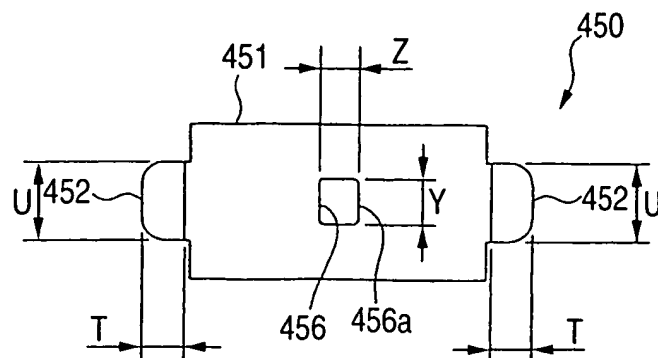


FIG. 31A

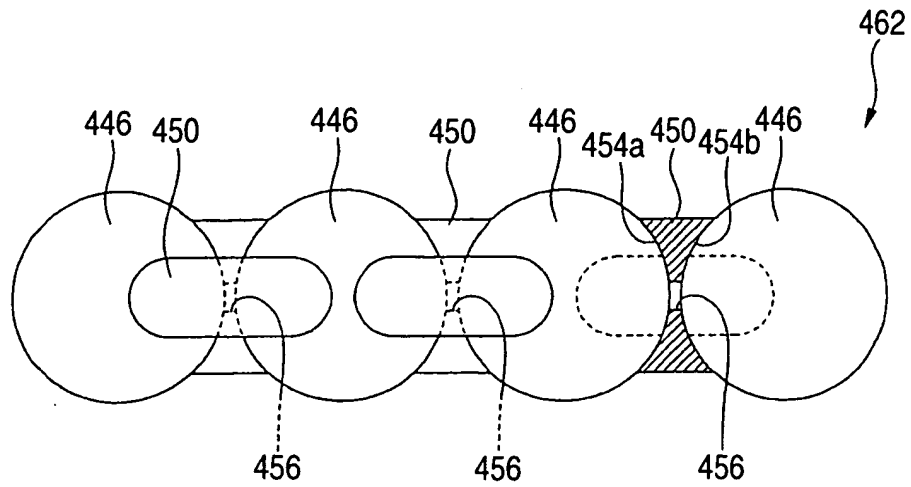
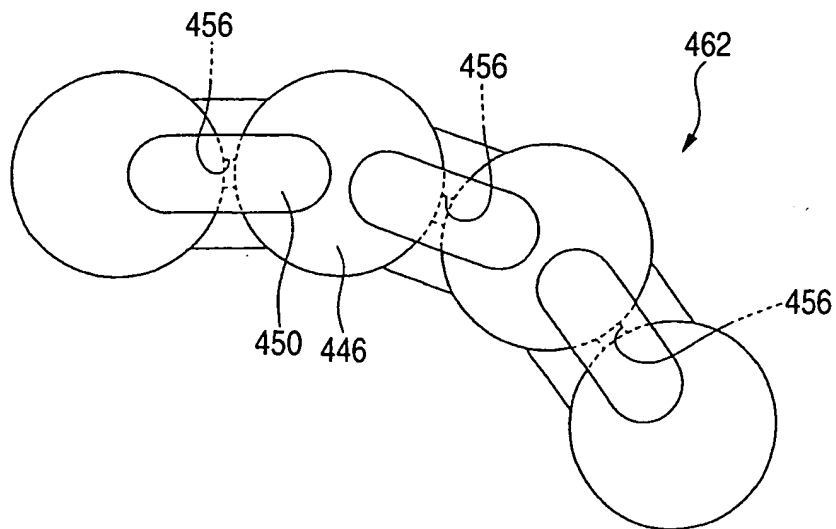


FIG. 31B



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FIG. 32B

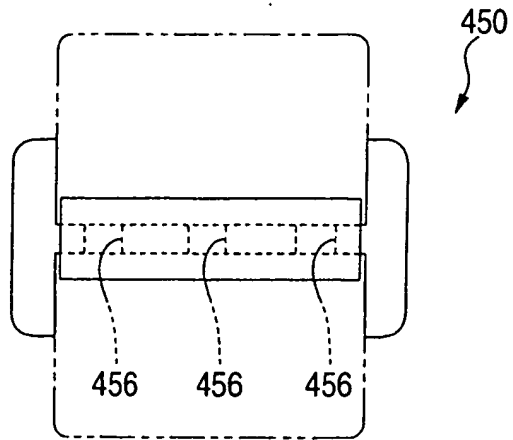


FIG. 32C

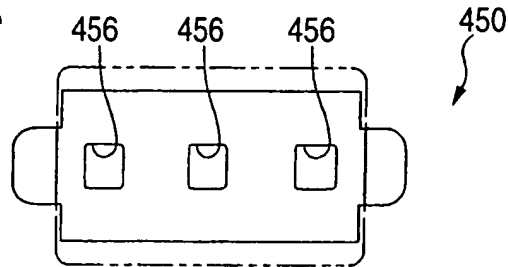


FIG. 33B

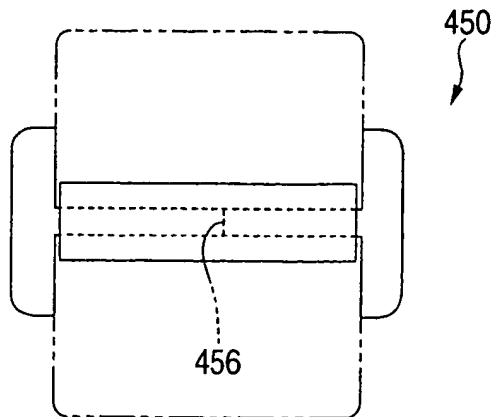
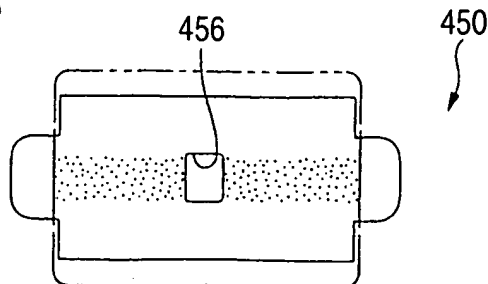


FIG. 33C



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FIG. 34B

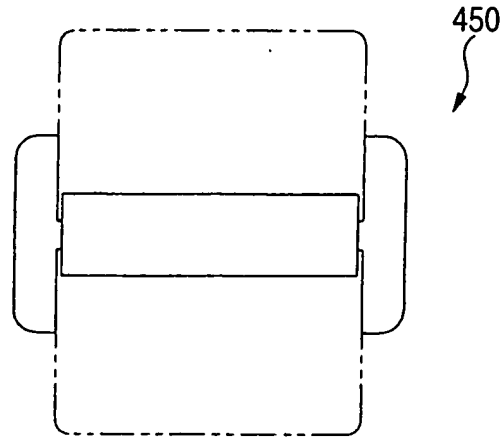


FIG. 34C

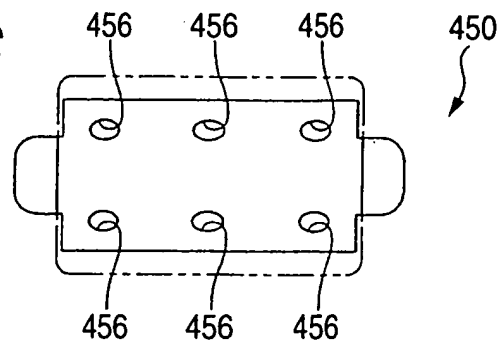


FIG. 35B

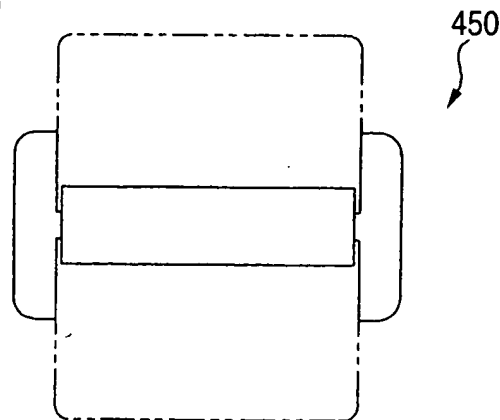


FIG. 35C

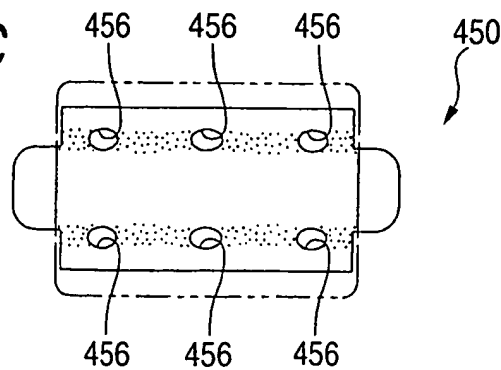


FIG. 36A

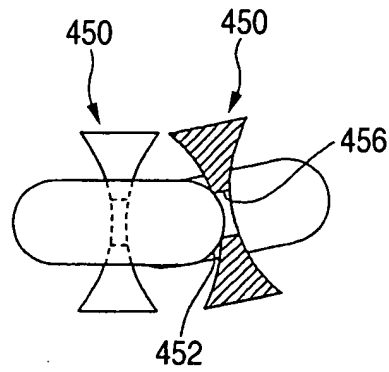


FIG. 36B

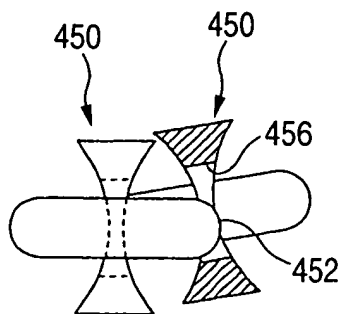


FIG. 37

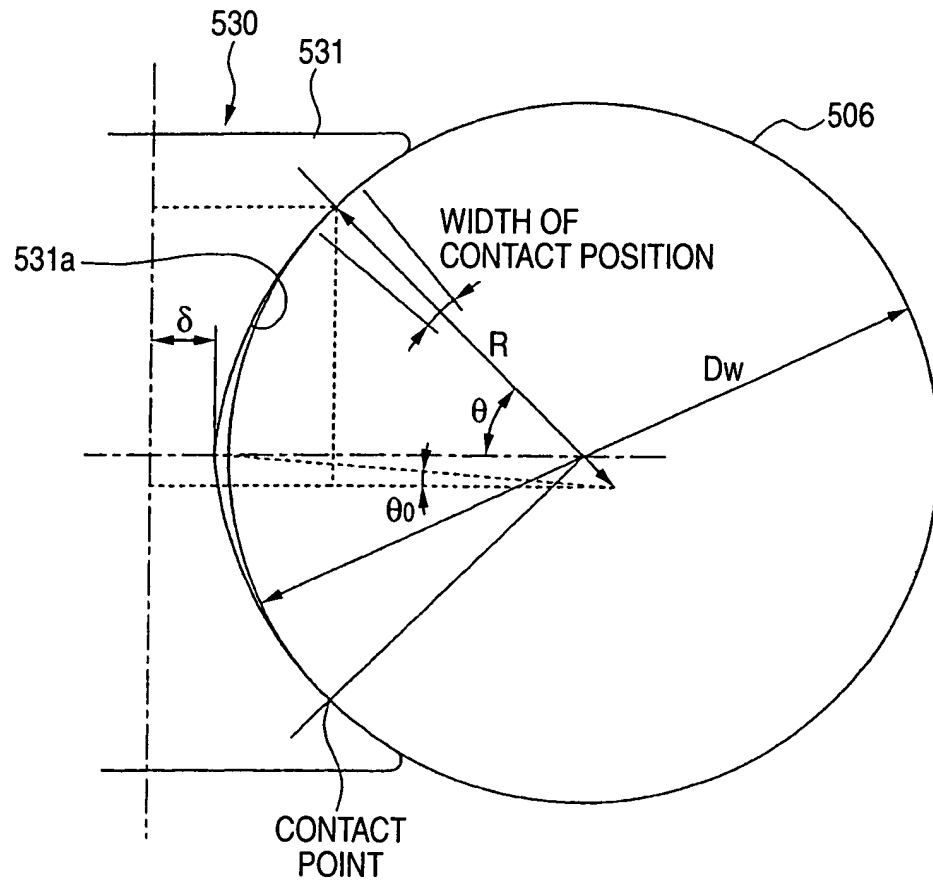


FIG. 38

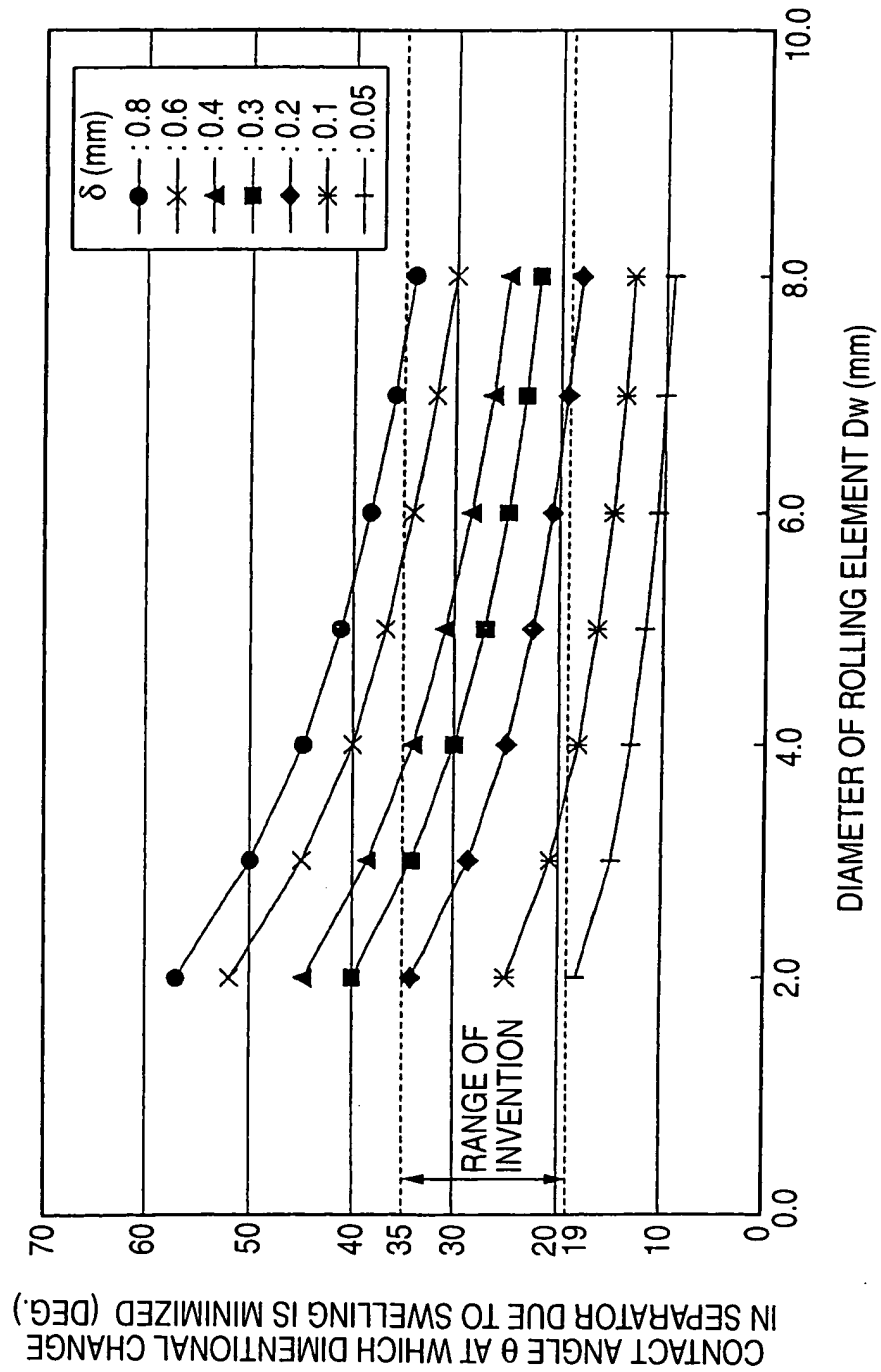


FIG. 39

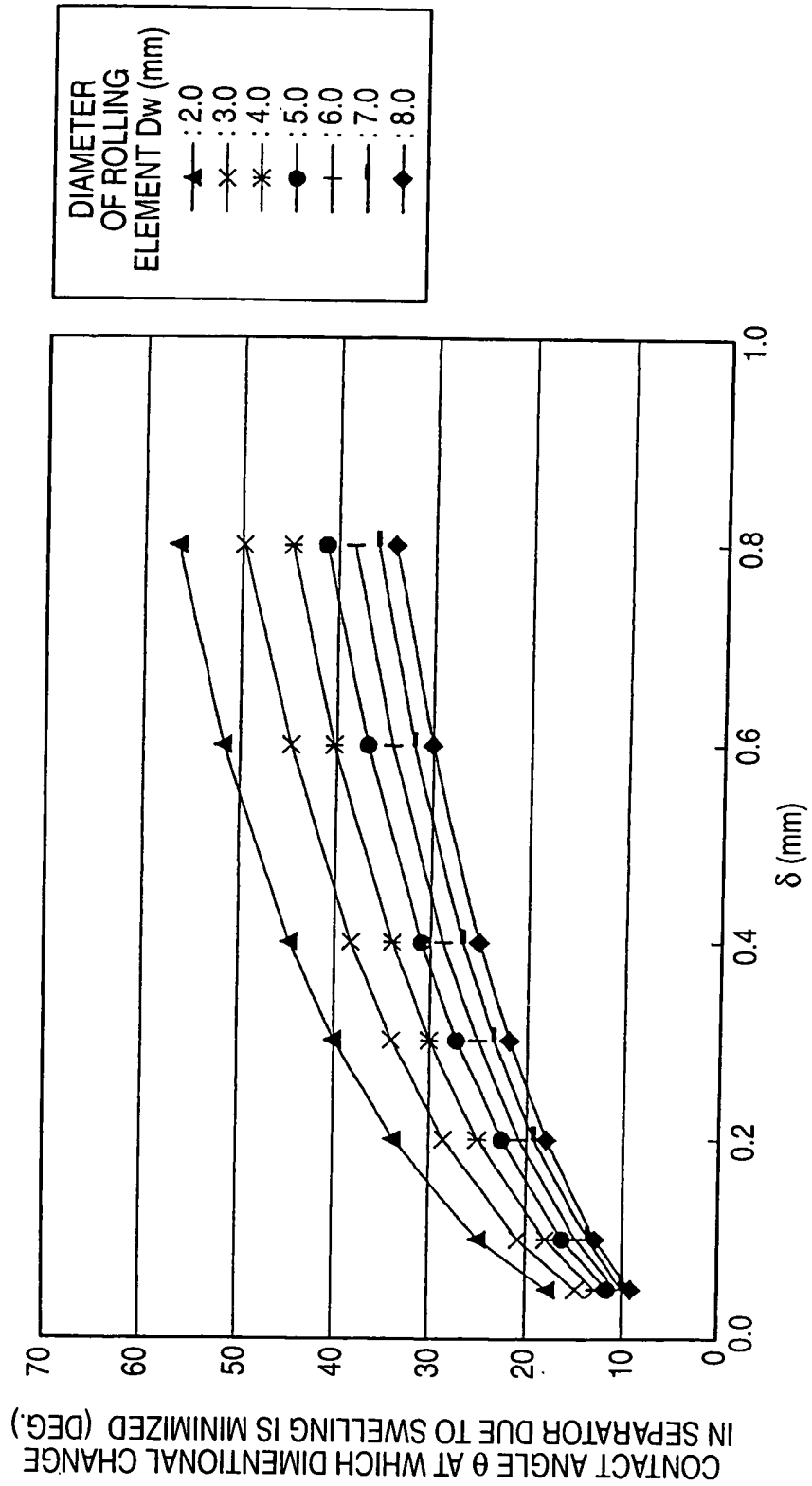


FIG. 40

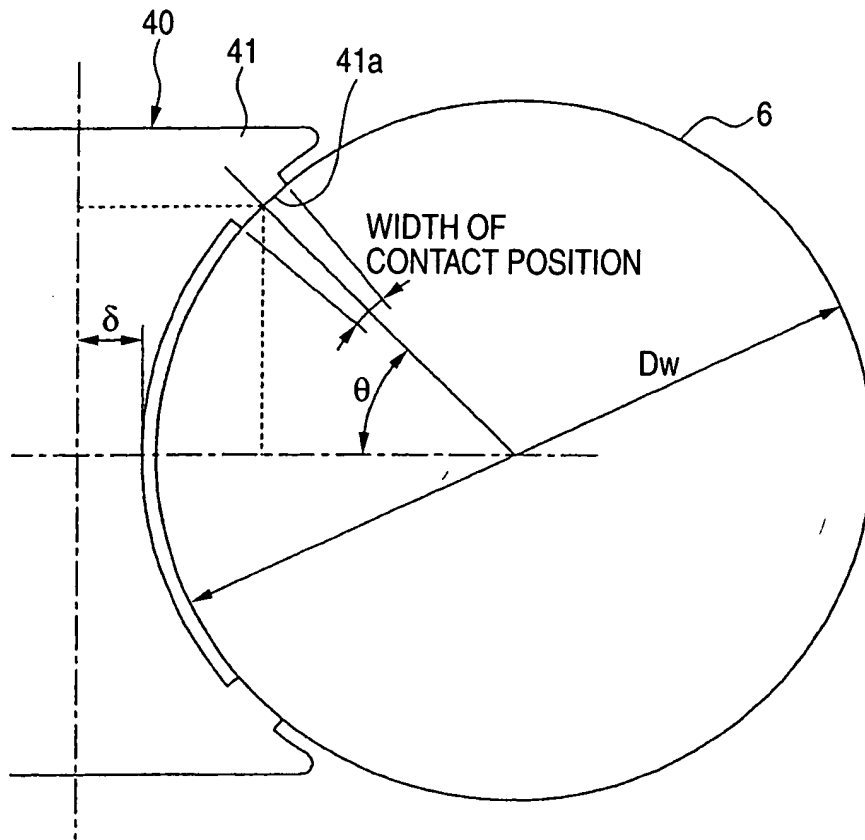


FIG. 41

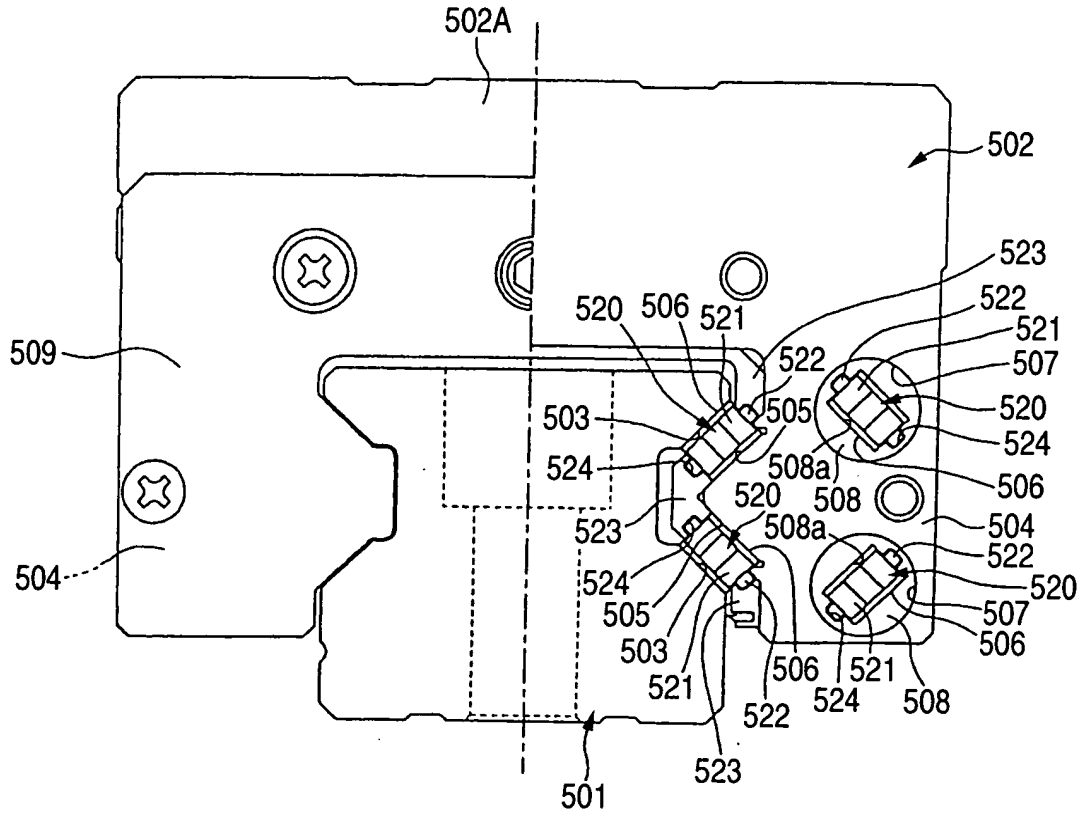


FIG. 42A

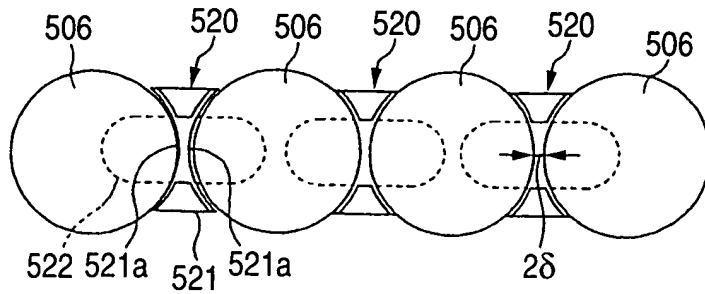


FIG. 42B

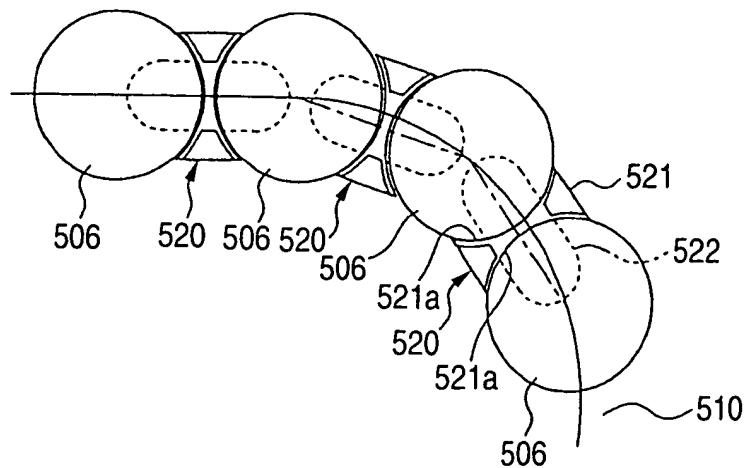


FIG. 43

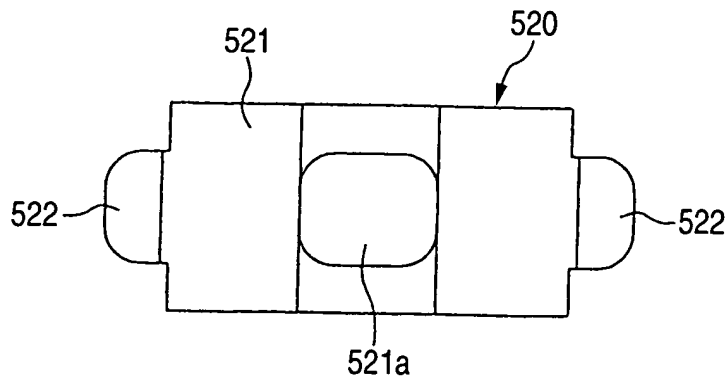


FIG. 44

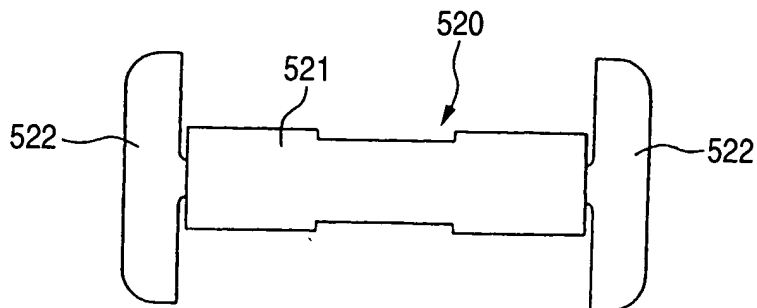


FIG. 45

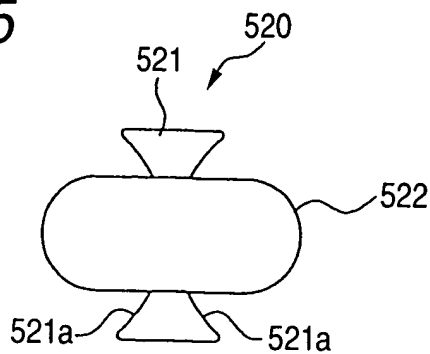


FIG. 46

